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Qualification of dynamic analyses of dams and their equipments
and of probabilistic assessment seismic hazard in Europe
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Session : Soils properties and simplified analysis

REVISITING SARMA'S METHOD FOR THE SEISMIC RESPONSE OF EMBANKMENTS ON SOFT SOILS: PRELIMINARY RESULTS FROM A PARAMETRIC STUDY



FRAMEWORK



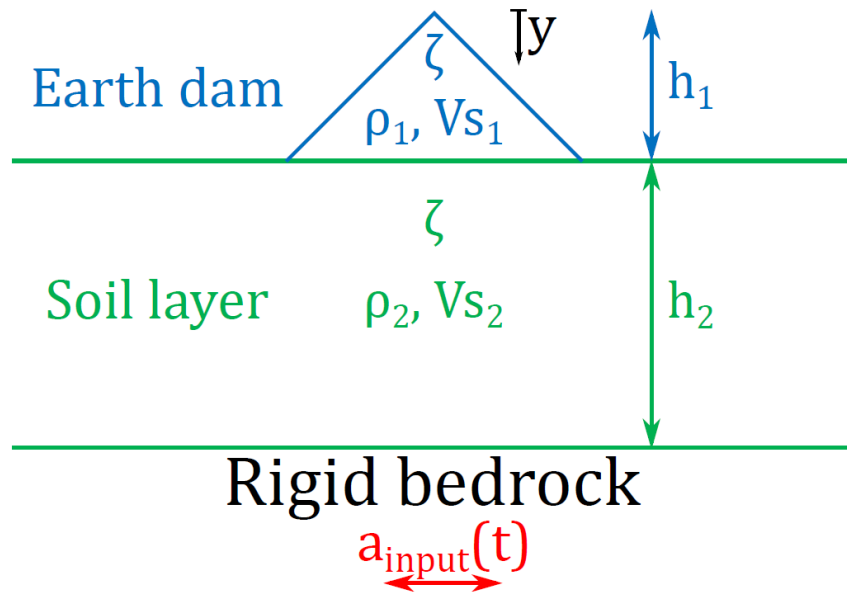
- **Simplified methods to get seismic coefficients/damages are attractive...**
 - Easy
 - Fast
 - Affordable
- **... especially for seismic assessment of embankments...**
 - Large length along rivers
- **... but are they reliable ?**
- **What is the possible safety margin to consider ?**

NO LIQUEFACTION

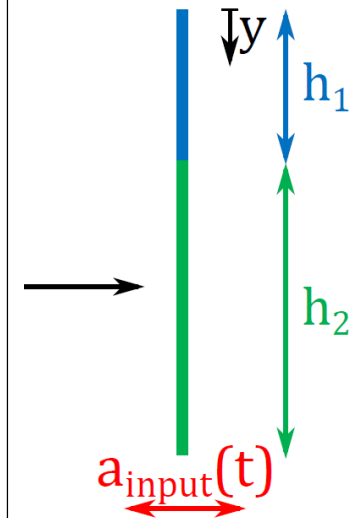
Revisiting Sarma's method | 2016

SARMA'S METHOD (1/3)

Assumptions:



- Linear viscoelastic, viscous damping (same damping in the dam and in the layer of foundation)
- Rigid bedrock
- Shear beam approach: only horizontal displacements and simple shearing deformations + uniform shear strains across the dam



Motion equations:

$$\frac{\partial^2 u_1}{\partial y^2}(y, t) + \frac{1}{y} \frac{\partial u_1}{\partial y}(y, t) = \frac{1}{V_{S1}^2} (\ddot{u}_1 + \zeta \dot{u}_1 + a_{input}(t))$$

$$\frac{\partial^2 u_2}{\partial y^2}(y, t) + = \frac{1}{V_{S2}^2} (\ddot{u}_2 + \zeta \dot{u}_2 + a_{input}(t))$$

$$m = \frac{\rho_1 V_{S1}}{\rho_2 V_{S2}} \text{ (impedance contrast)}$$

$$q = \frac{V_{S1} h_2}{V_{S2} h_1} \text{ (contrast in time to cross the layer/embankment)}$$

SARMA'S METHOD (2/3)

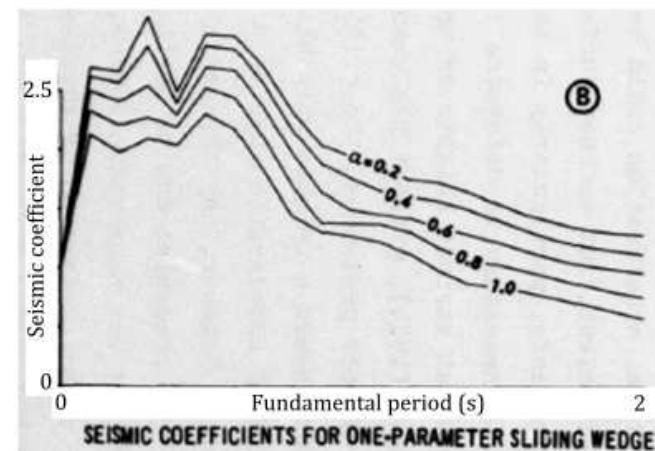
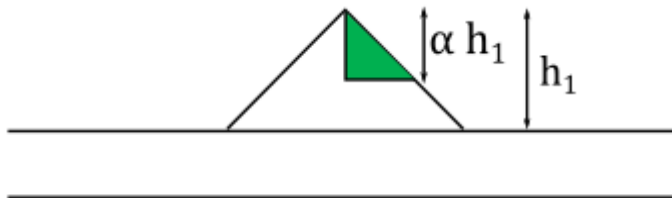
■ Main analytical results:

- Resonance frequencies:
For the n^{th} mode: $\omega_{0n} = \frac{\bar{a}_n v s_1}{h_1}$ where: $\frac{J_0(\bar{a}_n)}{J_1(\bar{a}_n)} = m \tan(q\bar{a}_n)$
- Mode shapes: $\Phi_n(y)$ in the embankment and $\Psi_n(y)$ in the layer for the n^{th} mode
- Displacements (and then accelerations):

$$u_1(y, t) = \sum_{n=1}^{\infty} \Phi_n(y) S_{dn}(t) \quad \text{and} \quad u_2(y, t) = \sum_{n=1}^{\infty} \Psi_n(y) S_{dn}(t)$$

■ Design curves:

- Deduced from analytical results, considering several combinations of parameters m and q , 9 real accelerograms and a viscous damping of 20%
- Example for $m=0.5$ and $q=0.75$:



SARMA'S METHOD (3/3)

- **Three main attractive features of this simplified method:**
 - It is not limited to the few cases solved to get the design curves
 - It takes into account an underlying layer of soil (mostly the case for embankments)
 - It may be possible to improve it by modifying some assumptions

ISSUES OF THIS WORK

- What are the possible limits of the assumptions made in Sarma's method ?
- Is the dynamic behavior predicted by Sarma's method realistic ?
- What possible safety margin could be associated to this method?

Limits imposed

- Work limited to dynamic response (strains and accelerations) → no estimation of damages (displacements)
- Direct use of the analytical results obtained by Sarma → no utilization of the design curves deduced from the analytical resolution

SUMMARY

1.INTRODUCTION

2.METHODOLOGY

PARAMETRIC STUDY

NUMERICAL ANALYSIS

APPLICATION OF SARMA'S METHOD

3.RESULTS

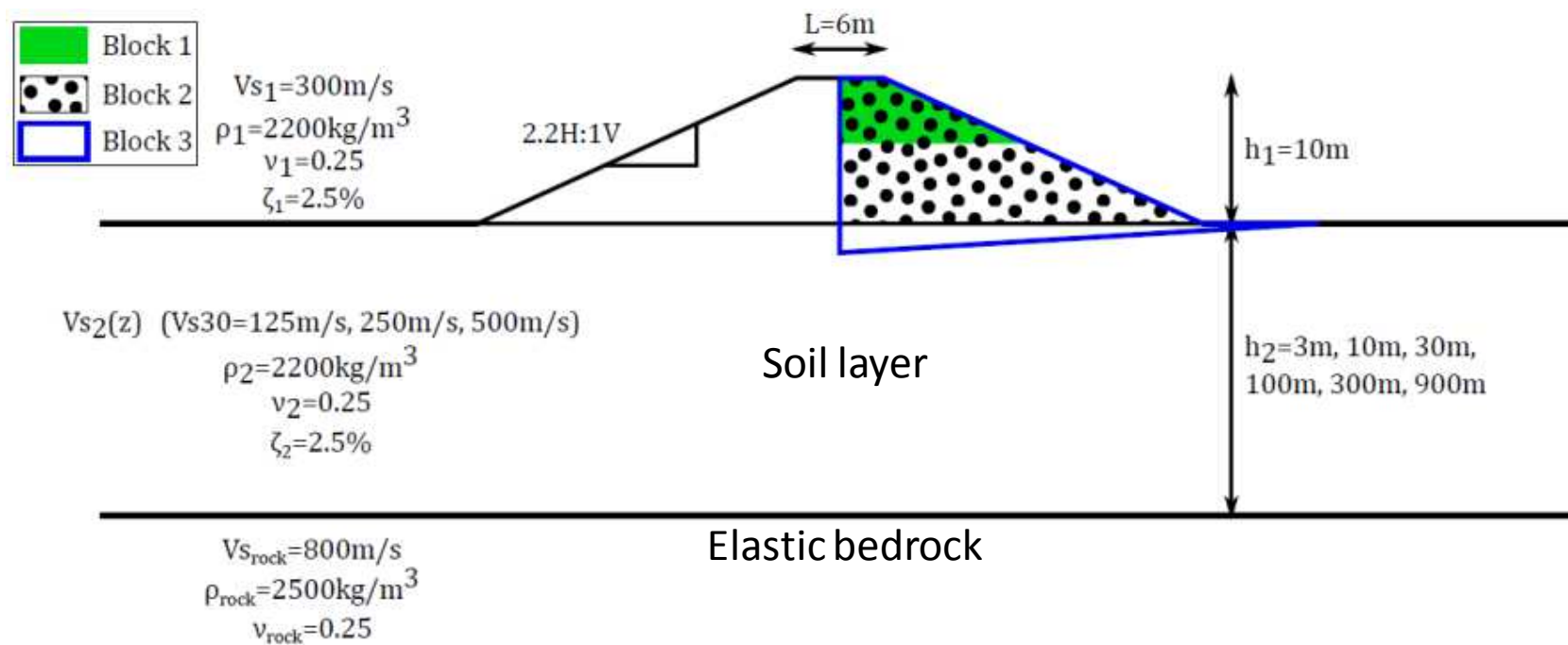
4.CONCLUSIONS

2. METHODOLOGY

→ **Comparison between numerical results and results given by Sarma's method**

PARAMETRIC STUDY (1/3)

- **18 geometries for the comparison :**
 - 6 thicknesses of soil layer : 3m, 10m, 30m, 100m, 300m and 900m
 - 3 values of V_{s30} in soil layers : 125m/s, 250m/s and 500m/s



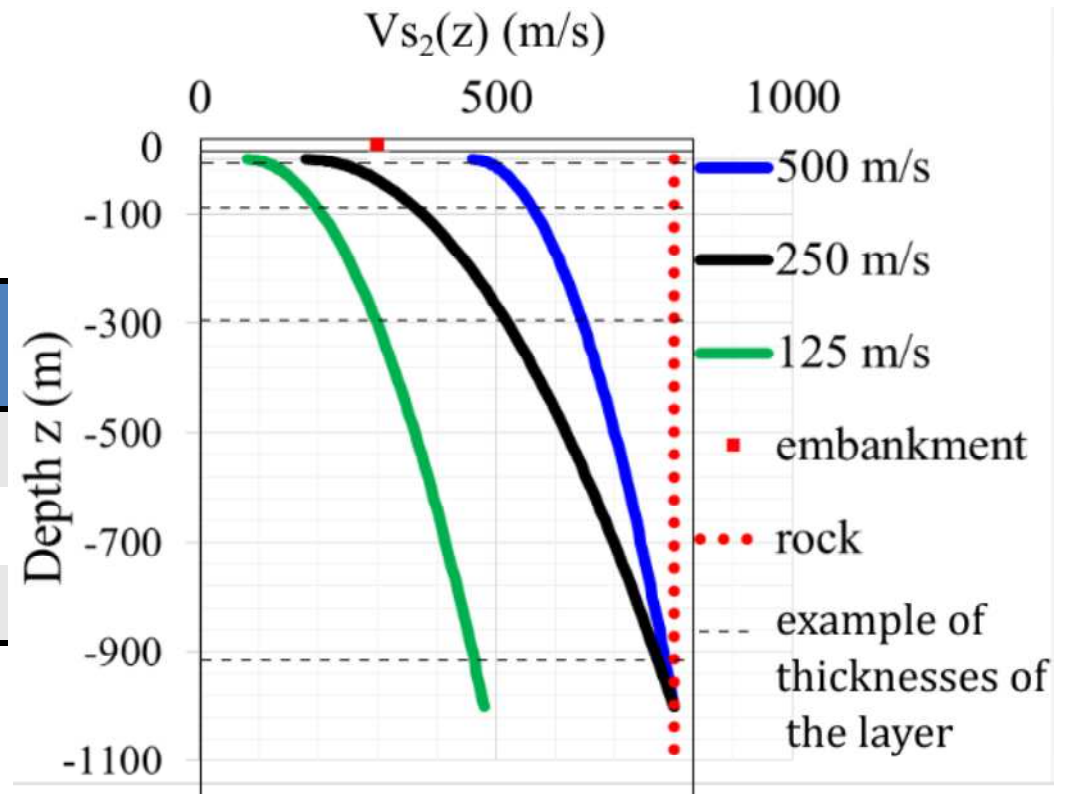
PARAMETRIC STUDY (2/3)

- Velocity gradients :

$$Vs_2(z) = Vs_a + (Vs_b - Vs_a) \sqrt{\frac{z - z_a}{z_b - z_a}}$$

$z_a = 0m ; z_b = 1000m$

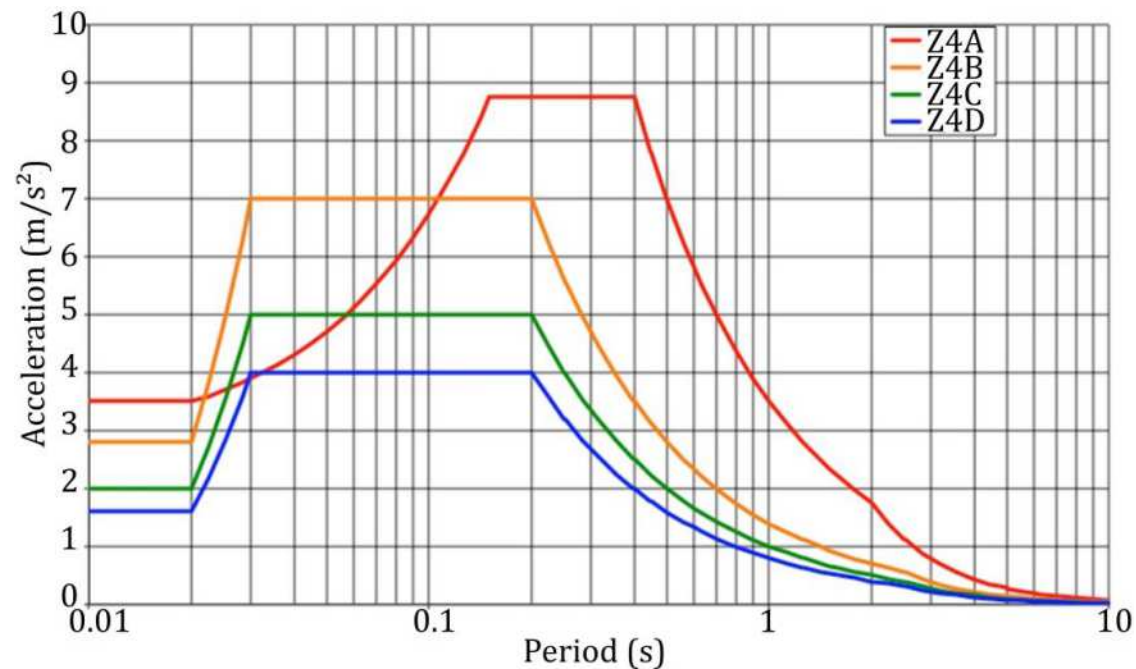
Vs_{30} (m/s)	Vs_a (m/s) at $z=z_a=0m$	Vs_b (m/s) at $z=z_b=1000m$
125	80	480
250	160	950
500	434	1000



PARAMETRIC STUDY (3/3)

Input accelerograms :

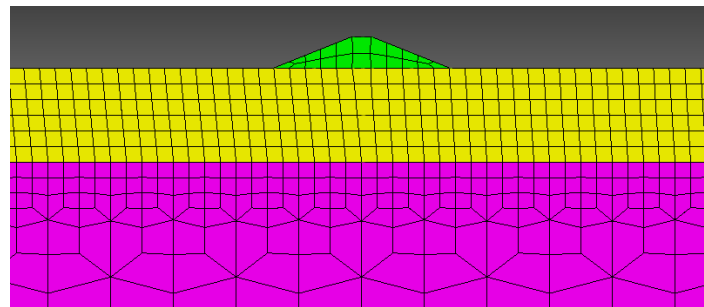
- 26 real accelerograms (horizontal component)
- Fitted on French design spectra (based on Eurocode 8): design spectra Z4D, Z4C, Z4B and Z4A (6 or 7 accelerograms per design spectra)
- Magnitude from 4.5 to 6



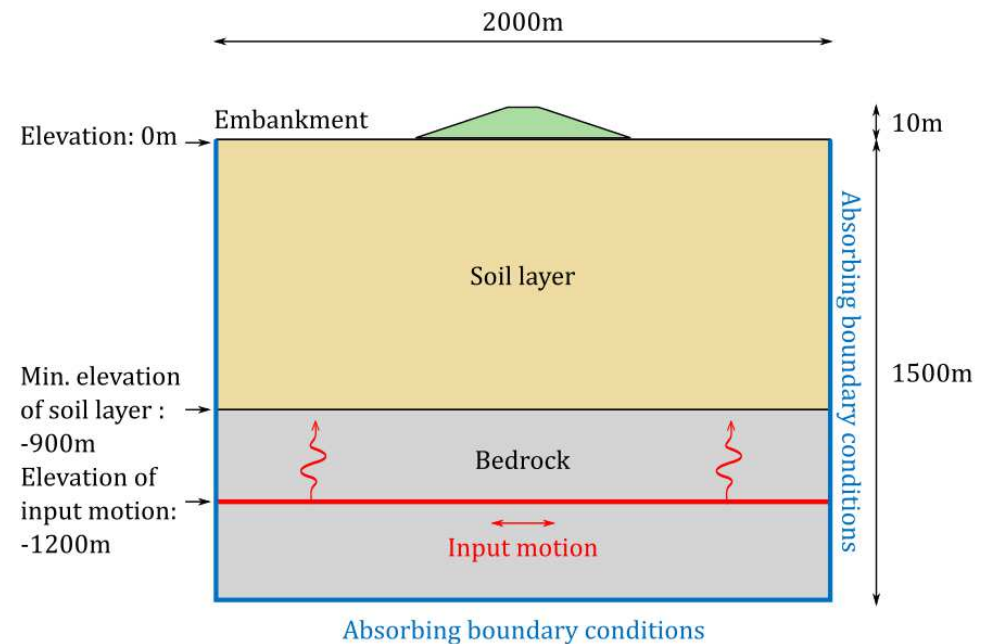
METHODOLOGY

NUMERICAL ANALYSIS (1/2)

- 2D spectral-element solver SPECFEM 2D
- Spectral element method in space (polynomial order $N=4$)
- Explicit 2nd order finite-difference method in time
- Mesh: quadrangles, size function of V_s value \rightarrow max. frequency=30Hz



Example: Layer of 30m, $V_{s30}=250\text{m/s}$



NUMERICAL ANALYSIS (2/2)

- **Receivers**

- Data are saved at each receiver

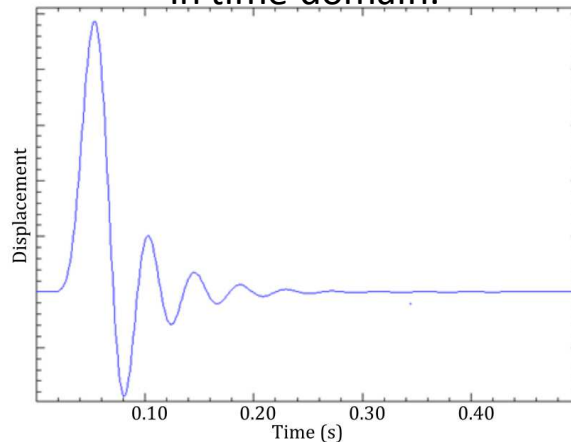
Horizontal velocity: V_x

Spatial derivatives: $\frac{dU_z}{dx}$ and $\frac{dU_x}{dz}$

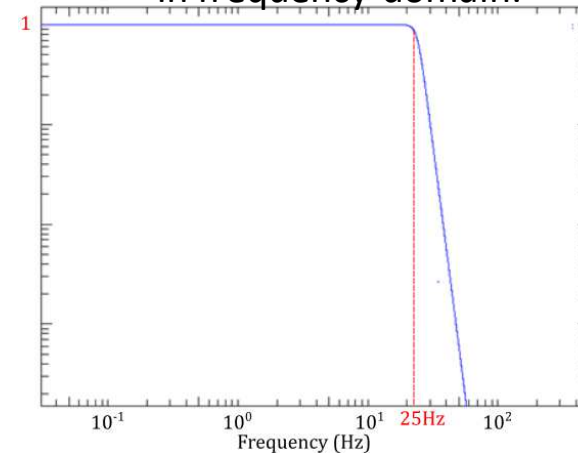
→ Shear strain: $\gamma = \frac{1}{2} \left(\frac{dU_z}{dx} + \frac{dU_x}{dz} \right)$

- **Impulse response to a Dirac fonction**

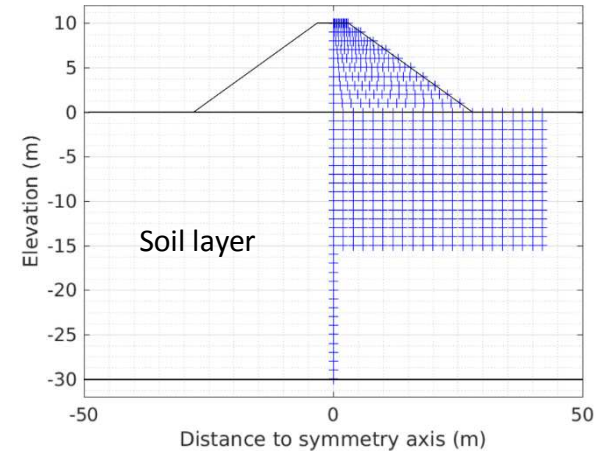
In time domain:



In frequency domain:

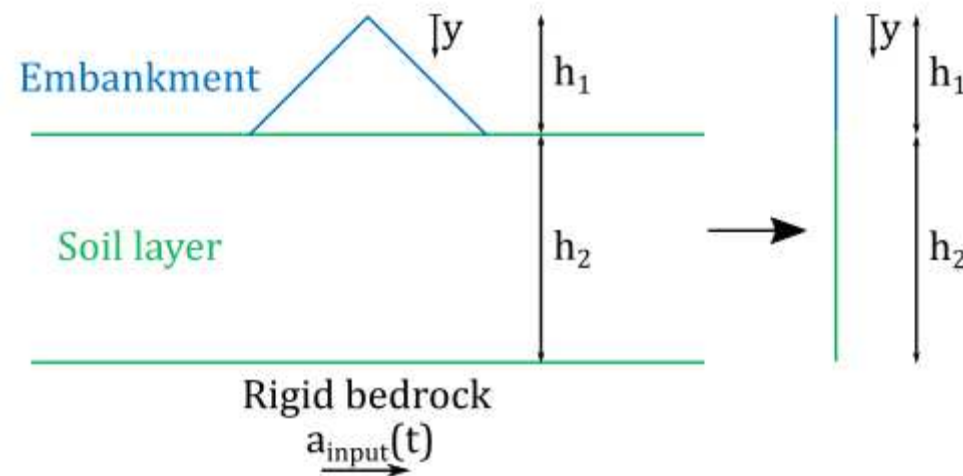


- **Convolution with the 26 accelerograms → accelerations and strains in each case at each receiver**



APPLICATION OF SARMA'S METHOD

- Use of analytical results from Sarma's method
- Use of the 26 chosen accelerograms as inputs
- No velocity gradient (assumption of an homogenous layer) → use of V_{s30} values
- No lateral variations in the response → the motion is calculated every 1m along the vertical axis



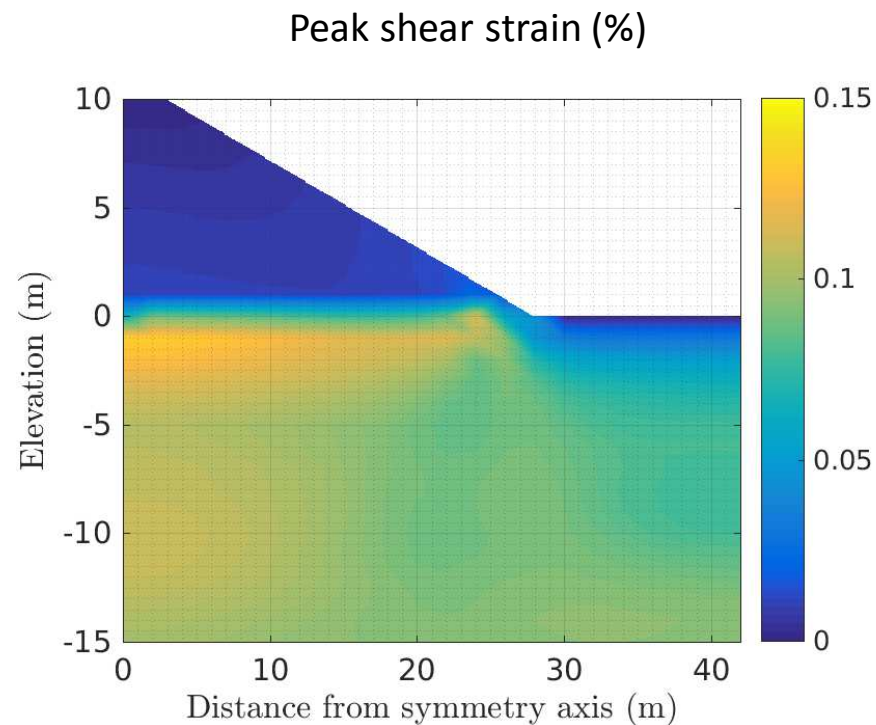
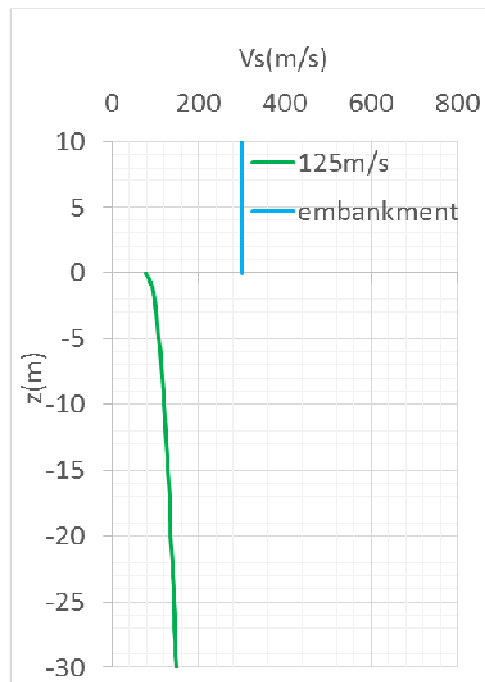
3. RESULTS

RESULTS

SHEAR STRAINS (1/3)

- Main results shown by numerical analysis

Example: peak shear strain reached at each point (not synchronous) – mean values (6 accelerograms) for the design spectra Z4B (PGA = 0.29g)

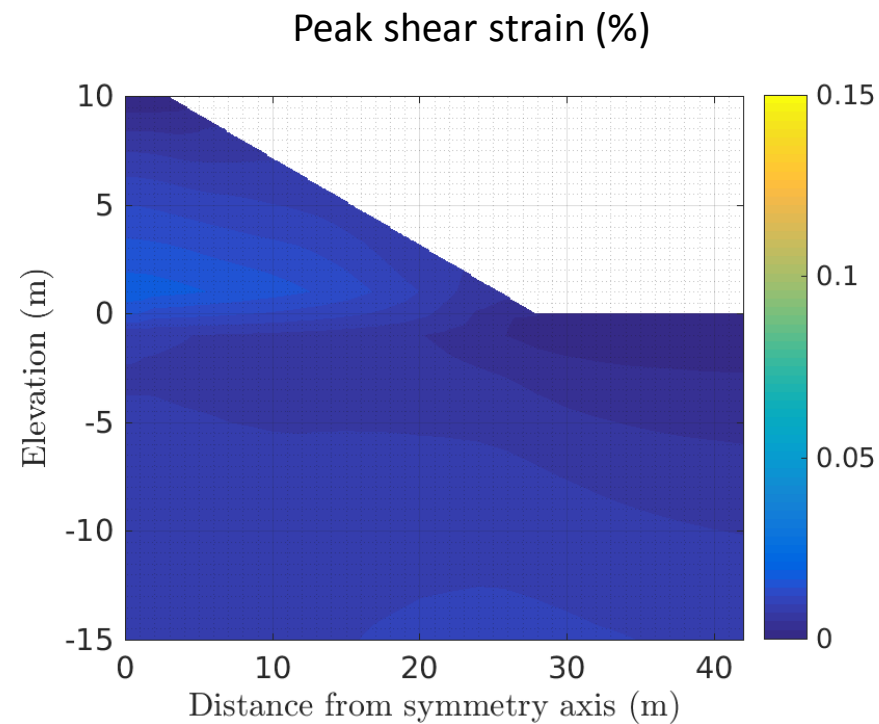
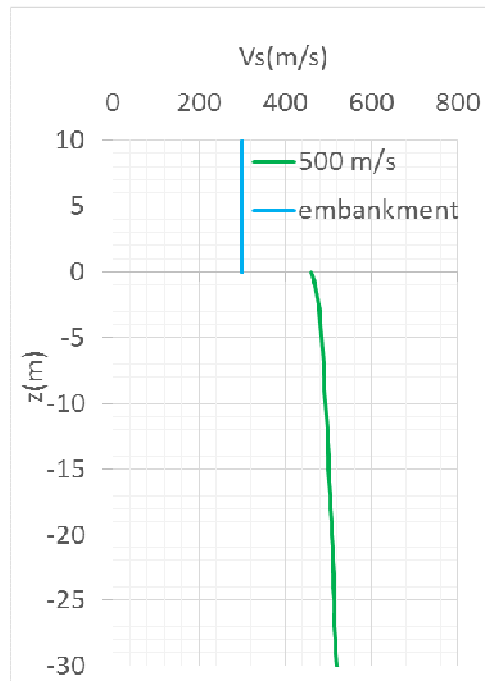


RESULTS

SHEAR STRAINS (2/3)

- Main results shown by numerical analysis

Example: peak shear strain reached at each point (not synchronous) – mean values (6 accelerograms) for the design spectra Z4B (PGA = 0.29g)



RESULTS

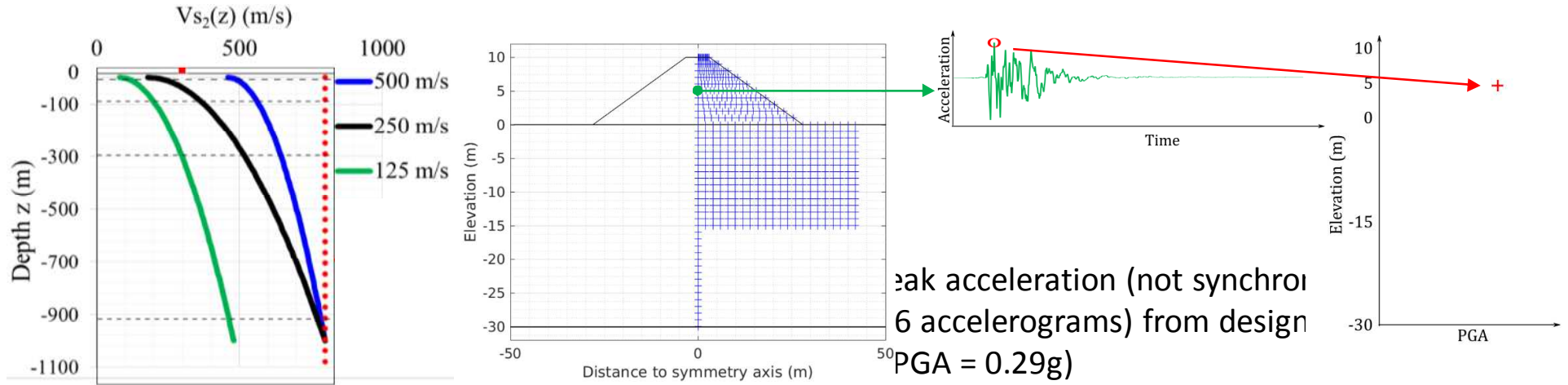
SHEAR STRAINS (3/3)

▪ Main results shown by numerical analysis

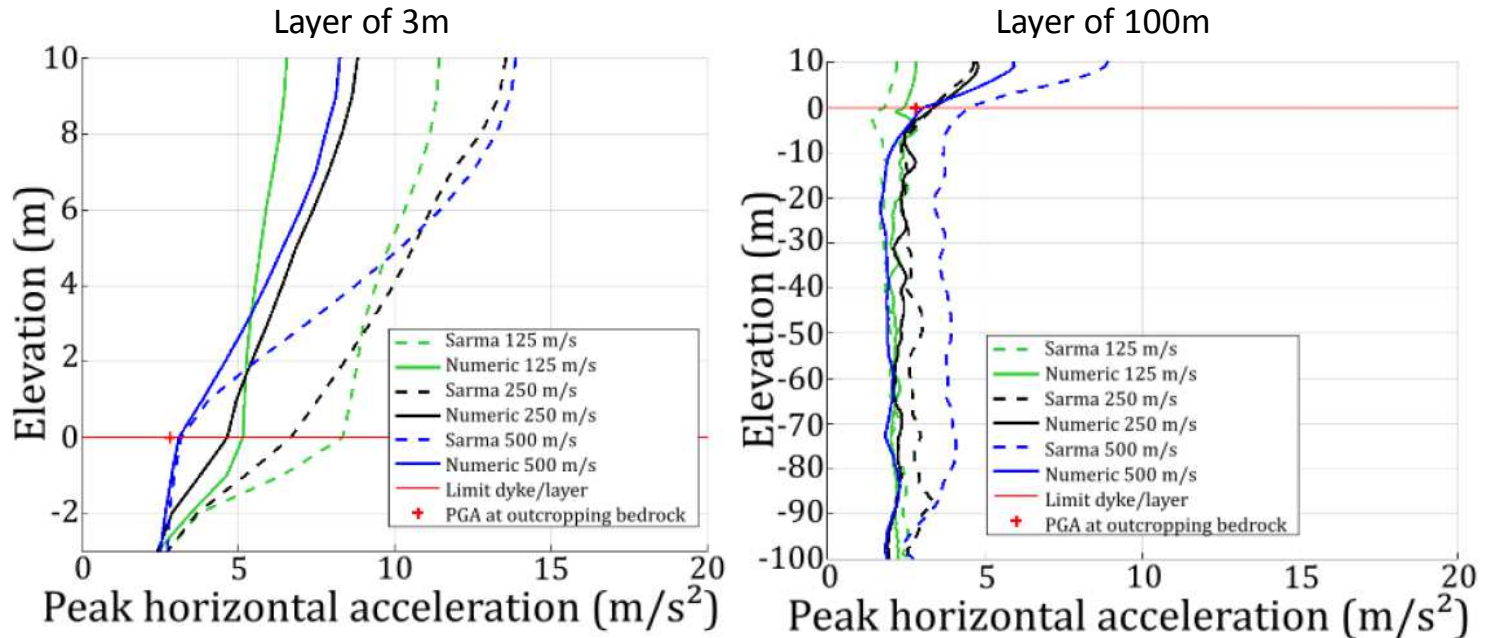
- Peak shear strains remain globally the same at a given elevation (to the advantage of the shear beam assumption)
- Peak shear strains are mostly controlled by shear modulus values ($\leftrightarrow V_s$), for a given loading level
- In all non-linear constitutive models, damping is related to shear strains \rightarrow for strong loadings, it may be unrealistic to consider an homogeneous viscous damping (the same in the embankment and the soil layer)

RESULTS

ACCELERATIONS: COMPARISON WITH SARMA (1/4)



Peak acceleration (not synchronous with 6 accelerograms) from design
 PGA = 0.29g

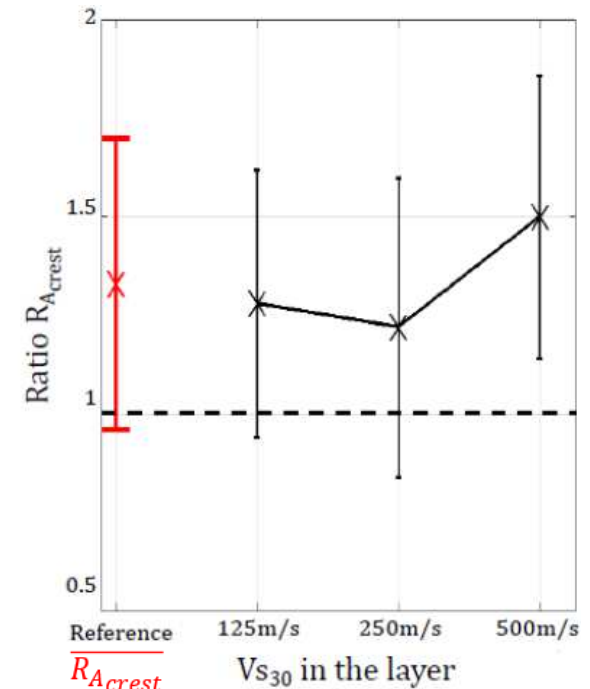
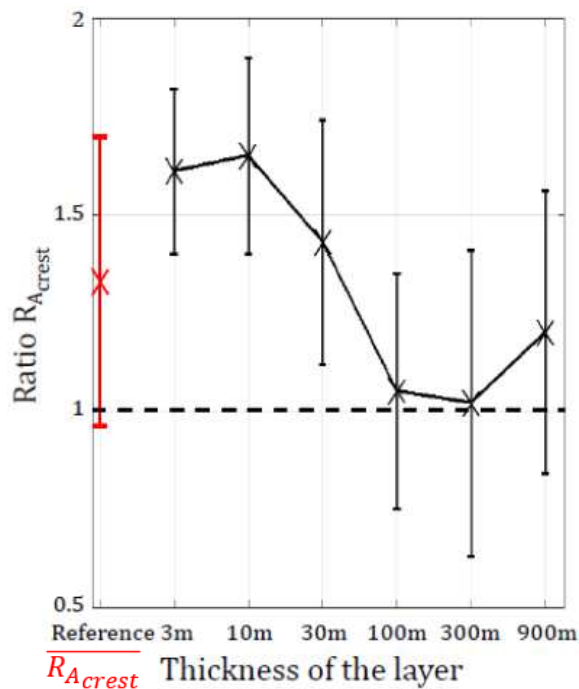
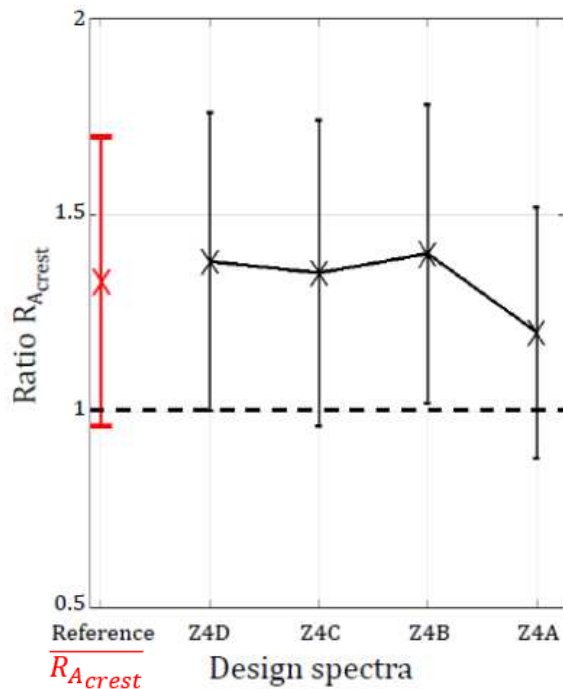


ACCELERATIONS: COMPARISON WITH SARMA (2/4)

- Quantification of the error on peak acceleration at crest:

$$\text{Ratio } R_{A_{crest}} = \frac{\text{Peak acceleration at crest from Sarma}}{\text{Peak acceleration at crest from numerical analysis}}$$

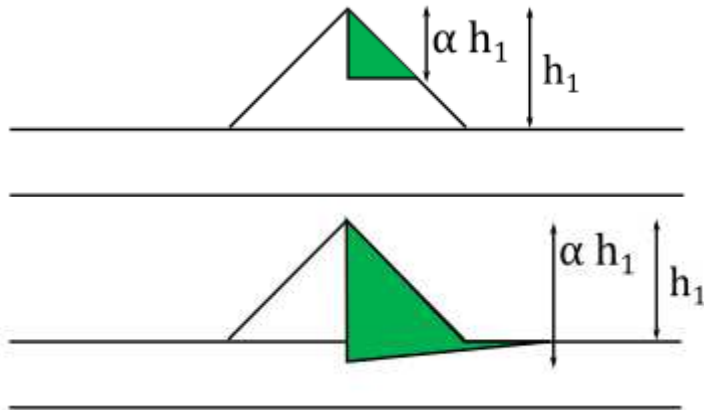
Mean value (all cases): $\overline{R_{A_{crest}}} = 1.33, \sigma = 0.37$



ACCELERATIONS: COMPARISON WITH SARMA (3/4)

- Quantification of the error on peak acceleration of a possible sliding block:

$$\text{Ratio } R_{A_{block}} = \frac{\text{Peak acceleration of the block from Sarma}}{\text{Peak acceleration of the block from numerical analysis}}$$



alpha	$\overline{R_{A_{block}}}$	σ
0.5	1.40	0.39
1	1.44	0.38
1.2	1.49	0.39

ACCELERATIONS: COMPARISON WITH SARMA (4/4)

- **Main results shown by the comparison:**
 - Trend (attenuation/amplification) of the dynamic response is well caught by Sarma's simplified method
 - Sarma's method leads globally to an overestimation of peak acceleration at crest (by 30% in average) and mean acceleration of a possible sliding block (by 40-50% in average).
 - The discrepancies may be explained by:
 - The assumption of a rigid bedrock
 - The assumption of an horizontal motion (far from the reality for higher modes)
 - The non-consideration of the velocity gradient in the soil layer

3. CONCLUSIONS

CONCLUSIONS

MAIN RESULTS

- **About assumptions made in Sarma's method:**
 - Rigid bedrock → infinite impedance contrast, greater amplification, no radiation of the energy in the bedrock
 - Shear beam assumptions → less accurate at higher frequencies. According to Gazetas(1987), this can explain the discrepancies regarding peak acceleration at crest.
 - Homogeneous viscous damping → the damping could be different in the embankment and the soil layer, according to the shear modulus values

- **About the dynamic behavior obtained when using Sarma's method**
 - Behavior realistic: trend of attenuation/amplification similar to numerical analysis

- **About the possible safety margins (on peak accelerations):**
 - In most cases, larger amplification of the input especially for soil layers relatively thin (3 to 30m)
 - In average, the seismic coefficient is overestimated by a factor of 50%
 - The thickness of the layer has a large influence on the possible safety margin (greater effect of the velocity gradient ?)

CONCLUSIONS

LIMITATIONS AND PERSPECTIVES

- **Impact of the velocity gradient ?**
 - Adapt Sarma's equations to take into account a velocity gradient ?

- **Effect of compaction of the layer by the embankment ?**
 - Consider V_s values in the layer more realistic in numerical analysis
 - In Sarma's simplified method, it is not specified where should be chosen the $V_s(z)$ profile (far or under the embankment)

- **Model damping in numerical analysis ?**
 - Major impact on the results: large attenuation, especially for thicker layer
 - Not realistic to always choose the same value in the embankment and the soil layer
 - Linear equivalent analysis to find a more realistic value of damping ?

- **Design curves**
 - Sarma's design curves are developed for a viscous damping of 15%-20% (global value to also take into account radiation of energy)
 - What would be the results of a comparison between Sarma's simplified method (design curves) and numerical results (with a damping more realistic) ?

THANK YOU FOR
YOUR ATTENTION

